

1

### Particle-Particle Collision Model for Dispersed Gas-Particle Flows: Implementation and Validation

#### Björn Hussmann, Prof. Michael Pfitzner

Thermodynamics Institute University of the Federal Armed Forces Munich

Thomas Esch, Thomas Frank

**ANSYS** Germany

June 27<sup>th</sup>, 2006

# Universität

### Outline

- Introduction modelling of dispersed gas-solid flows
- Stochastic particle-particle collision model overview
- Algorithm of the collision model
- Validation of the collision model
  - Test case description
  - Comparison with experimental results
- Summary and advisable extensions



### Modelling of highly loaded dispersed gas-particle flows

- Two common techniques for dispersed gas-solid flows:
  - Euler-Euler
  - Euler-Lagrange
- Euler-Lagrange model is suitable only for dilute flows
  - two-way coupling
- For highly loaded gas-solid flows, four-way coupling is essential
  - interaction gas  $\leftrightarrow$  particle
  - momentum transfer between particles  $\rightarrow$  collisions
  - realisation by the presented model

Modelling of dispersed gas-particle flows

#### Stochastic particle-particle collision model

- Sequential trajectory calculation
- Presence of neighbouring particles is taken into account
- Creation of a virtual collision partner according to local statistical mean
  particle properties
- Calculation of a collision probability
- Random process decides whether or not a collision takes place
- If it occurs the collision is calculated deterministically
- Enormous computational effort by simultaneous tracing of all particles is avoided
- Collision model is of iterative nature

### Requirements for applicability

- High mass loading
- moderate volumetric concentration (<~ 20%)</li>
- Only binary collisions
  - inter-particle distance >> particle diameter
  - aerodynamic forces dominate
  - not suitable for fluidised beds
  - $\rho_P >> \rho_{Gas}$
- Spherical particles



#### Algorithm of the collision model (1)



Stochastic particle-particle collision model, algorithm



#### Algorithm of the collision model (2)



Stochastic particle-particle collision model, algorithm



#### Algorithm of the collision model (3)



![](_page_8_Picture_0.jpeg)

#### Instantaneous velocity of the virtual particle P2

- Velocity of P2 comprises:
  - a mean part from the local average values
  - a fluctuating part including a correlation term between the two particles due to Sommerfeld [3,4] and a random term

$$v'_{2,i} = R(\operatorname{St}_t) v'_{1,i} + \sigma_{P,i} \sqrt{1 - R(\operatorname{St}_t)^2} \xi$$

correlation function is determined by LES of a homogeneous isotropic turbulence field

$$R\left(\mathrm{St}_{t}\right) = \exp\left(-0.55\,\mathrm{St}_{t}^{0.4}\right)$$

- Angular velocity of the particle is calculated the same way
  - no correlation between particles

#### Instantaneous velocity of the virtual collision partner

#### Collision frequency, probability and time step

- Collision frequency depends on:
  - particle number density n<sub>P</sub>
  - diameters of real and fictitious particle
  - instantaneous velocities of both particles

$$f_c = \frac{\pi}{4} \left( d_{P1} + d_{P2} \right)^2 \left| \vec{v_1} - \vec{v_2} \right| \, n_P$$

• Collision probability  $\rightarrow$  function of collision frequency and time step

$$P_c = 1 - \exp\left(-f_c \,\Delta t\right)$$

- decision by means of a uniformly distributed random number
- Lagrangian time step  $\rightarrow$  limited for stability and accuracy reasons

$$\Delta t \le 0.05 \, \frac{1}{f_c}$$

Collision frequency, collision probability and time step

## Universität 🚱 München

Faculty of Aerospace Engineering Thermodynamics Institute Prof. Dr. rer. nat. M. Pfitzner, Prof. Dr.-Ing. Ch. Mundt

#### Position of the collision partner

- Stochastic determination
- Probability equally distributed over cross section

![](_page_10_Picture_5.jpeg)

#### Deterministic calculation of the collision

- Distinction between sliding and non-sliding collision
- Determination of transferred momentum

Position of the virtual collision partner and calculation of the collision

## Implementation in ANSYS CFX

- User Fortran subroutine in FORTRAN 77
- Link to the CFX solver by an interface provided by ANSYS
- Four-way coupling is made available for gas-solid flows
- The model is contained in the next version of CFX (11, Beta-status)

### **Current limitation**

- No particle rotational motion
- Simplified particle-wall collision treatment
- If this aspect is improved in future  $\rightarrow$  inter-particle collision model will account for angular velocities

## Universität

Faculty of Aerospace Engineering Thermodynamics Institute Prof. Dr. rer. nat. M. Pfitzner, Prof. Dr.-Ing. Ch. Mundt

## Validation by experiment of Fohanno & Oesterlé [6]

- Experiment was arranged exactly for this purpose
- Enforced crossing of trajectories
- Flow induced by gravitation
- Glass particles, d<sub>P</sub> = 3 mm
- $\rho_P = 2500 \text{ kg/m}^3$
- Collision effects dominate

![](_page_12_Figure_9.jpeg)

![](_page_12_Figure_10.jpeg)

#### Description of the validation experiment

![](_page_13_Picture_0.jpeg)

#### Comparison of particle trajectories:

![](_page_13_Figure_3.jpeg)

![](_page_14_Picture_0.jpeg)

#### Comparison of particle number density (with collision model):

![](_page_14_Figure_3.jpeg)

small mass flow rate,  $\alpha = 6.5 \cdot 10^{-4}$ 

large mass flow rate,  $\alpha = 1.9 \cdot 10^{-3}$ 

- 3 measuring planes
- Particle streak velocimetry (2D optical method)

Particle number density at small / large particle mass flow rate

![](_page_15_Picture_0.jpeg)

#### Grid refinement study and Lagrangian time step

- Coarse grid: 10500 elements, 30000 trajectories
- Fine grid: 620000 elements, 480000 trajectories
- Lagrangian time step depends on grid refinement
- Accuracy of variable fields is improved
- For equally good statistic → number of trajectories quadratic in number of elements

#### Study of grid refinement and Lagrangian time step

![](_page_16_Picture_0.jpeg)

Plane A

Plane B

Plane C

#### Measurement error and concentration profiles

![](_page_16_Figure_3.jpeg)

- Estimated measuring error:
  - 10-13% for mean values
  - 15-20% for standard deviations
- Particle concentration profiles from measurement & simulation:
  - for small and large mass flow rate
  - main source of error: inaccurate particle-wall treatment

#### Comparison of results: experiment and simulation – concentration profiles <sup>17</sup>

![](_page_17_Picture_0.jpeg)

#### Particle axial mean velocity profiles

![](_page_17_Figure_3.jpeg)

- Reason for deviations:
  - Favourable downward flow of air in the simulation
    - $\rightarrow$  reduction of drag and faster downstream of particles
  - Inadequate particle-wall collision treatment

![](_page_17_Figure_8.jpeg)

Comparison of results: axial mean velocity profiles of particles

![](_page_18_Picture_0.jpeg)

Plane A Plane B

Plane C

#### Particle velocity standard deviation in transverse direction

![](_page_18_Figure_3.jpeg)

- Deviation in plane A not allegeable by inaccurate particle-wall collision treatment
  - intense air turbulence or
  - non-uniform particle supply  $\rightarrow$  explanation but improbable
    - $\rightarrow$  likely caused by measurement errors
- Differences in planes B and  $C \rightarrow$  lower trajectory crossing point
- Fluctuations decrease with increasing mass flow rate

#### Comparison of results: velocity standard deviation in transverse direction <sup>19</sup>

![](_page_19_Picture_0.jpeg)

#### Particle absolute velocity in plane of visualisation

![](_page_19_Figure_3.jpeg)

- Almost no decrease of absolute velocity in simulation
- Noticeable decline in experiments
  - 3D effects of inter-particle collisions
  - dissipation effects due to inelastic collisions
  - conversion of translational in rotational energy (most probable)
  - dependent on collision frequency

Plane A Plane B Plane C

#### Comparison of results: absolute velocity in plane of visualisation

20

### Scatter plot of particle velocity fluctuations (exp.)

![](_page_20_Figure_2.jpeg)

der Bundeswehr

Universität 🚱 München

![](_page_20_Figure_3.jpeg)

![](_page_20_Figure_4.jpeg)

- Plane A: 2 types of trajectories:
  - vertically falling:  $\rightarrow 2^{nd}$  quadrant
  - oblique rebounding from wall:  $\rightarrow 4^{th}$  quadrant
- Panes B & C: 3 types of trajectories, symmetry:
  - vertically falling:
- → centre
  - rebounding from both walls:  $\rightarrow$  off-centre
- Plane C: considerable scatter
  - homogenisation of particle flow due to collisions

#### Experimental results: particle velocity fluctuations, small mass flow rate <sup>21</sup>

![](_page_20_Figure_15.jpeg)

![](_page_21_Picture_0.jpeg)

#### Scatter plot of particle velocity fluctuations (exp. & sim.)

![](_page_21_Figure_3.jpeg)

Comparison of results: scatter plots of particle velocity fluctuations

![](_page_22_Picture_0.jpeg)

#### Summary and advisable extensions (1)

- Application of a collision model for highly loaded dispersed gasparticle flows is indispensable
- Qualitatively correct prediction of
  - particle velocity profiles
  - homogenisation of the particle flow
  - attenuation of velocity fluctuations
  - influence of the mass flow rate
- Deviations due to
  - insufficiently accurate particle-wall collision modelling
  - no particle rotation
  - no rotation induced lift force (Magnus-effect)
  - no shear induced lift force (Saffman-force)

![](_page_23_Picture_0.jpeg)

#### Summary and advisable extensions (2)

- Comparison with simulations by Pachler [7] of the same experiment including particle rotation shows a slight improvement of the results
- Better predictability [7] with model extension by Sommerfeld [3]
- In flows dominated by particle-wall collisions, particle rotation should be included, as the 3 other validation cases accomplished suggest
- Providing of detailed results in scope of engineering accuracy
- Distinct advancement without enhancing the effort considerably

![](_page_24_Picture_0.jpeg)

![](_page_25_Picture_0.jpeg)

#### Stochastic particle-particle collision model

- Model was derived by Oesterlé & Petitjean [1,2]
- Extension to consideration of correlated particle motions by Sommerfeld [3,4]
- Detailed formulation by Frank [5]

[1] Oesterlé, B. and A. Petitjean: Simulation of particle-to-particle interactions in gas-solid flows.
 In: Proceeding of The International Conference on Multiphase Flows, Tsukuba, Japan, September 24-27 1991.
 [2] Oesterlé, B. and A. Petitjean: Simulation of particle-to-particle interactions in gas-solid flows.
 Int. J. of Multiphase Flow, 19(1):199-211, 1993.
 [3] Sommerfeld, M.: Modellierung und numerische Berechnung von partikelbeladenen Strömungen mit Hilfe des Euler-Lagrange-Verfahrens.
 Shaker Verlag, Aachen, 1996. Universität Erlangen/Nürnberg, Habilitation thesis.
 [4] Sommerfeld, M.: Validation of a stochastic Lagrangian modelling approach for inter-particle collisions in homogeneous isotropic turbulence.
 Int. J. of Multiphase Flow, 27:1829-1858, 2001.
 [5] Frank, Th.: Parallele Algorithmen für die numerische Simulation dreidimensionaler, disperser Mehrphasenströmungen und deren Anwendungen in der Verfahrenstechnik. Shaker-Verlag, Aachen, 2002. Chemnitz University of Technology, Habilitation thesis.
 [6] Fohanno S. & B. Oesterlé: Analysis of the effect of collisions on the gravitational motion of large particles in a vertical duct.
 Int. J. of Multiphase Flow, 26:267-292, 2000
 [7] Pachler, K.: Parallele Berechnung 3-dimensionaler, instationärer Gas-Partikel-Strömungen unter Berücksichtigung von Kollisionen und Aggregatzustandsänderungen.
 Shaker Verlag, Aachen, 2004. Technische Universität Chemnitz, Dissertation.

Stochastic particle-particle collision model, literature

## Universität

Faculty of Aerospace Engineering Thermodynamics Institute Prof. Dr. rer. nat. M. Pfitzner, Prof. Dr.-Ing. Ch. Mundt

#### Further test cases

- Test case 2: Vertical pipe flow by Tsuji et al. [8]
- Test case 3: Rectangular particle laden jet flow by Sommerfeld [9]
- Test case 4: Swirling particle laden flow by Zhou et al. [10]

![](_page_26_Picture_6.jpeg)

[8] Tsuji, Y., Morikawa Y. and H. Shiomi: *LDV measurements of an air-solid two-phase flow in a vertical pipe*. Journal of Fluid Mechanics, 139:417-434, 1984.
[9] Sommerfeld, M.: *Particle dispersion in turbulent flow: the effect of particle size distribution*. Particle and Particle Systems Characterization, 7:209-220, 1990
[10] Zhou, L.X., Y. Li, T. Chen and Y. Xu: *Studies of the effect of swirl numbers on strongly swirling turbulent gas-particle flows using a phase-Doppler particle anemometer*. Powder Technology, 112:79-86, 2000

Further test cases for validation